



Key Features:

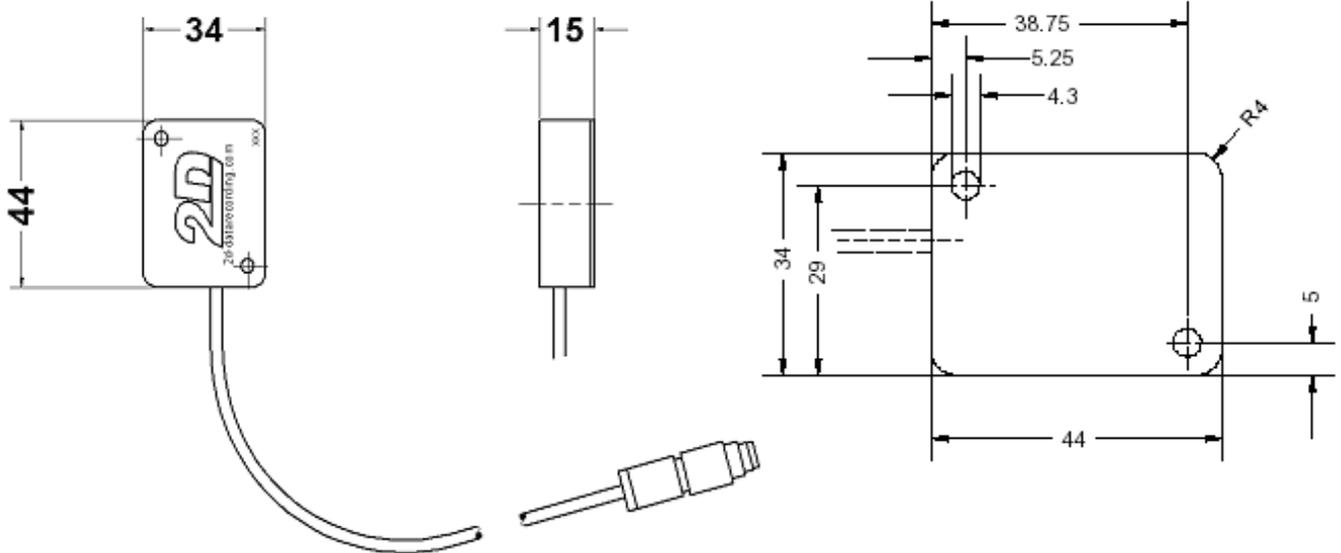
- *3 axis acceleration sensor with extreme accurate axis alignment*
- *Direct high speed AD conversion on module*
- *Calibration, temperature compensation and physical unit calculation done by microcontroller*
- *Calculation of complex output channels based on recalculation with channels on CAN bus*
- *Additional output channels with preselected filters*
- *With integrated gyro possibility for direct Bankangle signal*
- *Also available as 6 axis unit with additional 3 gyros*
- *Output of physical values onto the CAN-bus*

Based on newest MEMS technology 2D integrated a 3 axis acceleration sensor module + 1(3) axis Gyro with a high power CAN controller to start a new generation

BC-3Axx_zGyyy-000

Box CAN, 3 axis accelerometer, 1(3) GYRO

Dimensions



CAN identifier allocation

| CAN ID (default) | | | | | | | | |
|------------------|-----------|--------|----------------|--------|------------|--------|------------|--------|
| CAN-ID | Byte 0 | Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 | Byte 6 | Byte 7 |
| 0x498 | ACC_X | | ACC_Y | | ACC_Z | | GYRO_X | |
| 0x499 | T_CPU | | COUNT_LIFE | | GYRO_Y | | GYRO_Z | |
| 0x000* | ACC_X_IIR | | ACC_Y_IIR | | ACC_Z_IIR | | GYRO_X_IIR | |
| 0x000* | T_CPU_IIR | | COUNT_LIFE_IIR | | GYRO_Y_IIR | | GYRO_Z_IIR | |

*optional

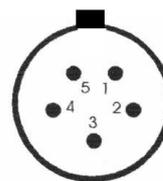
Formulas to calculate physical values

| Channel | Multiplicator | Offset | Channel | Multiplicator | Offset |
|---------|---------------|--------------------|---------|---------------|-------------------|
| ACC_X | = 0,005 | * digits - 163,835 | GYRO_X | = 0,02 | * digits - 655,34 |
| ACC_Y | = 0,005 | * digits - 163,835 | GYRO_Y | = 0,02 | * digits - 655,34 |
| ACC_Z | = 0,005 | * digits - 163,835 | GYRO_Z | = 0,02 | * digits - 655,34 |
| T_CPU | = 0,1 | * digits - 0 | | | |

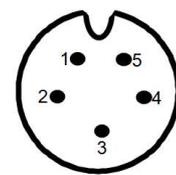
Connector Layout

Connector type

| Pin | Name | Description | Color |
|-----|-------|------------------|-------|
| 1 | CAN H | CAN Bus High | White |
| 2 | CAN L | CAN Bus Low | Green |
| 3 | GND | Ground | Black |
| 4 | n.c. | Not Connected | - |
| 5 | Vext | Power IN (8-18V) | red |



Binder 719, 5 PF (front side)



Binder 719, 5 PM (front side)

On request some options are possible for the CAN-line connector of all 2D CAN modules. Please take a look at the product group [Connectors] in the 2D Product catalog.

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Supplement Sheet

The Figure shown beneath shows the “correct directions” for the accelerometers in three directions (x, y and z) as well as the three (optional) included gyros. The directions are essential if you calibrate this sensor using Wint.

